

Investigation into Friction-Induced Vibration Characteristics of Electromagnetic Brake in High-Load Logistics Robots

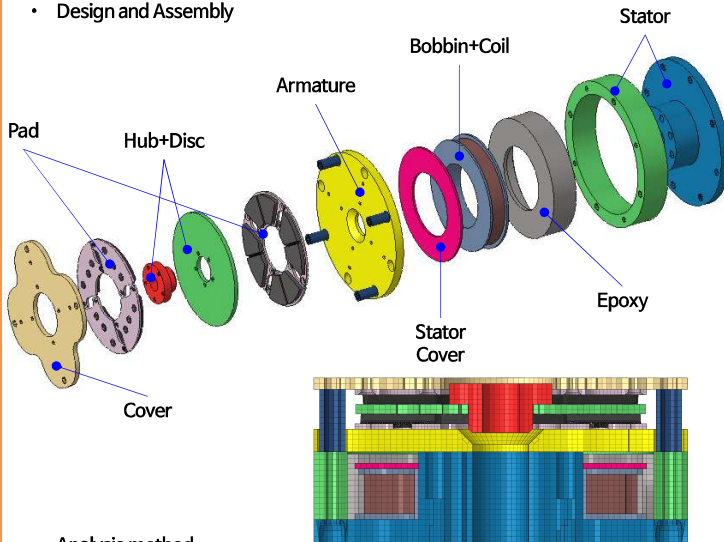
Sung-yuk Kim, Seongjoo Lee, Shin-Wook Kim, Seongyun Yoo

BACKGROUND

- **Background**
 - The acceleration of industrial machinery electrification, driven by the mandate to achieve net-zero carbon emissions by 2050, has triggered an unprecedented surge in demand for high-capacity logistics robots capable of handling payloads exceeding 2 tons.
 - **Core Mechanism**
 - To ensure operational efficiency and human safety, these high-load robotic platforms employ a dual-braking architecture composed of regenerative braking for routine deceleration and power-off electromagnetic brakes as a critical fail-safe mechanism for emergency stopping and positional holding.
 - **Research Necessity**
 - Despite the high criticality of these systems, the technical stability and vibrational reliability of power-off electromagnetic brakes under high-load conditions remain relatively underexplored, necessitating a comprehensive investigation into their mechanical behavior.
- © **Research objective:** Investigating the frictional vibration behavior of electromagnetic brakes specifically designed for high-load logistics applications

METHODS

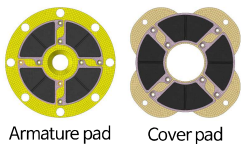
Design and Assembly



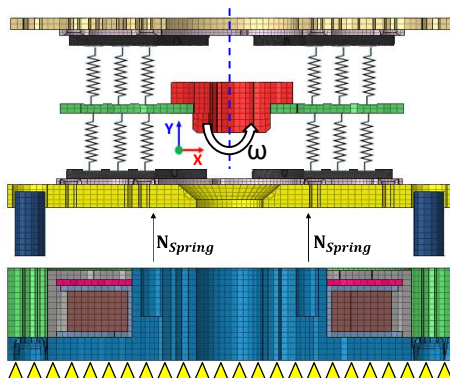
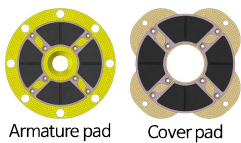
Analysis method

- Vibration instability analysis
 - Method: Complex eigenvalue analysis
 - Friction coefficient: 0~0.45
 - Force: 2,938.68 N (8 compression springs)

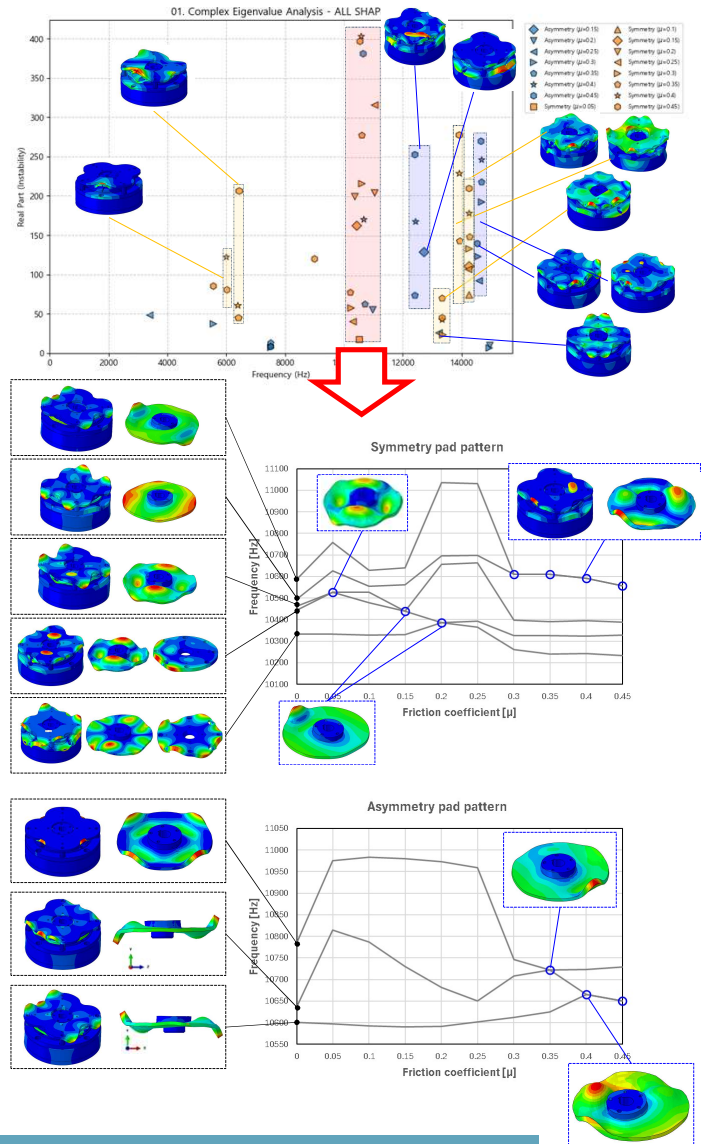
Case 1. Symmetry Pad



Case 2. Asymmetry Pad



RESULTS/DISCUSSION



CONCLUSIONS

- Vibrational instability regions vary distinctly depending on the pad arrangement (symmetric vs. asymmetric) despite using identical friction materials.
- Finite element analysis identifies out-of-plane bending modes of the axisymmetrically assembled components (cover, disc, and armature) as the primary cause of instability.
- The symmetric configuration exhibits unstable modes over a wider frequency spectrum, suggesting that structural symmetry can paradoxically facilitate multi-modal coupling.
- The dominant instability mode occurs in the 10 kHz band due to friction-induced coupling between the disc's doublet modes, triggering severe mode localization and asymmetric wave distortion.
- The degeneracy of doublet modes is broken into a distinct frequency split, driven by geometric perturbations and structural asymmetries from the hub keyway and bolt-fastening boundaries.
- Future braking tests will evaluate the qualitative and quantitative correlations between numerical predictions and experimental vibration spectra.
- ❖ This work was supported by the Technology Innovation Program (Development of Electronic Brake Series for Large Scale Mobile Robot Platform) (RS-2024-00432477) funded By the Ministry of Trade Industry & Energy (MOTIE, Korea)